

# Study on Smart Wheelchair based on Microcontroller for Physically Disabled Persons

Sandeep Kumar<sup>1</sup>, P. Raja<sup>2</sup>

<sup>1</sup>Ph.D Student, Electronics & Communication, OPJS University, Churu, Rajasthan, India

<sup>2</sup>Assistant Professor, Electronics & Communication, BRCM College Bahal, Bhiwani, India

**Abstract:** In recent year's enlargement promises a broad scale in developing smart wheelchair for those people disabled belonging to poor community. The research of smart wheelchair begins to depict awareness from both scientific community and industry. This paper includes the smart wheelchair that can monitor the possibility circumstances like temperature, humidity, fire etc... Be in command of voice, eye and joystick. This smart wheelchair informs the doctor/ analyzer via text message or through voice message about the patient conditions. In present world the medical field is center of attention about to be concerned the patients and hence this proposed product will be made user friendly to reduce the load of caretaker and will boost up the confidence level of the disabled person by making him/her self-dependent. The system is divided into 3 main units: Voice recognition through Mobile Phone, Eye Gesture recognition through Microcontroller and Motor control through Joystick. The whole coordination is based on grouping a Mobile Phone with a Microcontroller and Sensors.

**Keywords:** Automatic wheelchair, 8051 Microcontroller, LCD, Motor, Accelerometer, Analog Joystick, ADC, Ultrasonic Sensor, GSM Modem, Mobile Phone, Eye Gesture recognition and Voice Recognition.

## I. INTRODUCTION

Now a day's disabled persons in India, 21 million persons obtained through the most recent Population Census and National Sample Survey Organization's broad surveys on disability or we can say 2 percent of the total population in India. A new World Bank Report on disabled persons in India, has observed that, there is growing evidence that people with disabilities comprise between 5 and 8 per cent of the Indian population (around 55 – 90 million individuals). Although government and the public sector would have to play a key role in this Endeavour, it may be neither feasible, nor desirable for them to do it all. There are different types of disability, coupled with variations due to gender, class, place of residence (rural / urban) etc. Population Census and NSS surveys are the major two sources of official statistics in India. According to Census of India rate of disability increase rapidly every year as shown in figure below.

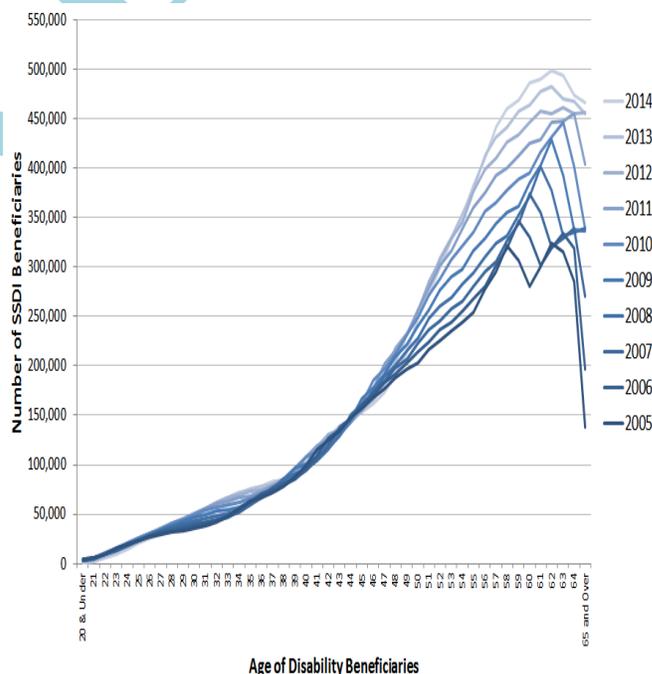
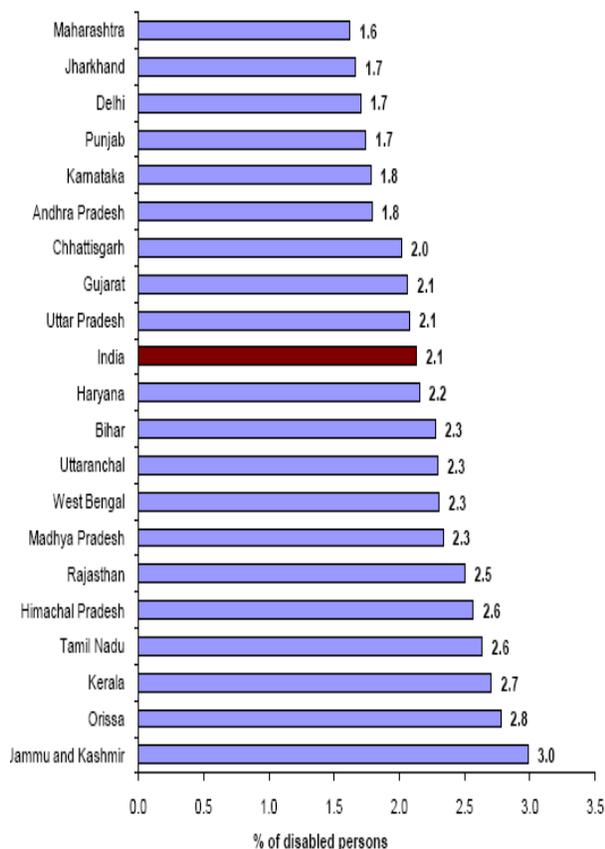


Fig 1: Growth rate of disabled person in India





**Fig 5:** Prevalence of disability in major states of India  
 Again, among males, the occurrence of disability (2.37%) was significantly higher than that among females (1.87%). The occurrence rate among SC population (2.23%) was marginally higher as compared to the general population; while among ST population, it was noticeably lower (1.92%). There were significant variations from Population Census findings with respect to their composition by type of disability.  
 The occurrence of disability in various states of India means percentage of disabled in total population was relatively much higher in Jammu & Kashmir (3%), Orissa (2.8%), Kerala (2.7%), Tamil Nadu and Himachal Pradesh (2.6% each) while it was relatively low in Maharashtra (1.6%), Jharkhand, Punjab and Delhi (1.7% each), Karnataka & Andhra Pradesh (1.8% each) etc. if we consider all the states of the country, the occurrence of disability in state population was highest in Sikkim (3.8%). Further, in terms of numbers, about half of the disabled were located in five states, i.e. Uttar Pradesh, Bihar, West Bengal, Tamil Nadu and Maharashtra. The number of disabled males was higher than that of disabled females in any state in general, except for the case of Tamil Nadu. According to the census 2011 fifty percent of the disabled were of age less than 30 and only twenty five percent of disabled persons were of age 50 or more. This is of serious

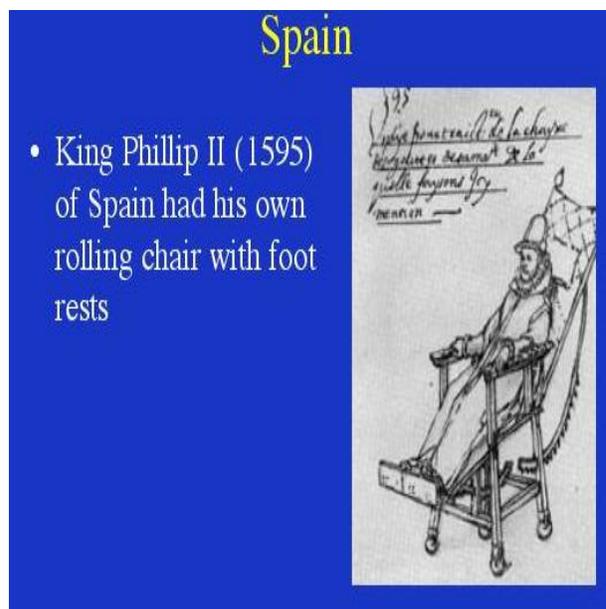
concern as most of the disabled persons were found to be very young.

The aim of the project is to use smart wheelchair easy to operate by using voice recognition, Eye gesture control and Analog Joystick. According to patient comfort any one of the device can controlled the wheelchair for moving forward, backward, left and right by Eye rotation or Analog joystick and voice recognition. A smart wheelchair is integrated with Ultrasonic sensors, temperature sensor, Mobile phone, motor and smoke sensor to help patient to achieve some self-directed mobility. The Ultrasonic sensors can help the patient control the smart wheelchair and avoiding the obstacles until the patient is able to handle the situation. The different type of approaches like human voice, Eye gesture movement and Mobile phone allow the patient to use synchronizes with the movement of wheelchair so that they can use it with comfort.

## II. LITERATURE REVIEW

### 2.1 History and Evolution of Wheel chair

In 15<sup>th</sup> century first wheelchair was invented by king of Spain called Phillip and name of that wheelchair was invalids chair. Afterward Stephen Farfler made three wheel chassis in 16<sup>th</sup> century as shown in figure 7 below. Later on John Dawson was invented by Bath wheel chair in 1783. In the year 1881 the push rims for self forward motion wheel chair was invented as shown in figure 9 below. In the year 1932, Harry Jennings built the first foldable wheel chair as shown in figure 10.



**Fig 6:** First wheelchair King Phillip II (1595)

## Self-propelled chair

- Paraplegic watchmaker, Stephen Farfler (1655) built his own chair at 22 yrs of age

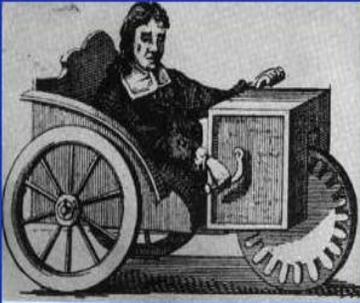


Fig 7: 16<sup>th</sup> Century wheelchair

## “Bath” chair

- Developed in Bath, England
- Invented by John Dawson, “Wheel-chair maker” 1783
- Dominated the market of 19<sup>th</sup> century
- Two large wheels, one small wheel



Fig 8: 17<sup>th</sup> Century wheelchair

## “Seating”

- Comfort for the disabled person became more of an issue
- Convertible chair (reclining back and adjustable foot rests)
- 18<sup>th</sup> century

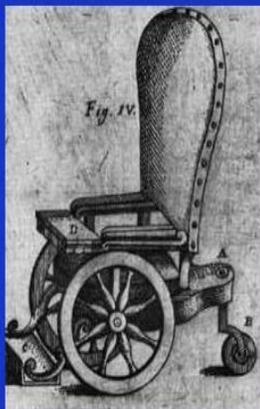


Fig 9: 18<sup>th</sup> Century wheelchair



Fig 10: 19<sup>th</sup> Century manual wheelchair



Fig 11: 19<sup>th</sup> Century Electric Powered wheelchair

## 2.2 Various Types of Wheel Chairs

Depends on the mode of power we have mainly two types of wheel chairs:

- Manual wheel chair
- Electric powered wheel chair

**Manual wheelchairs** or self-propelled wheelchairs are drive by the caretaker, usually by turning the large rear wheels like bicycle wheels are those that require human power to move them. Many manual wheelchairs are just as likely to be rigid framed with Light weight and due to light weight cost are high in the market. Transport wheelchairs are designed to be constrained by an assistant using the handles, and the back wheels are rimless and smaller. Transport chair is used to move a within a hospital or in areas where a user's standard chair is unavailable. These chairs are commonly seen in airports for disabled passengers to move from their seats on the plane. Manual wheelchairs are of different types:

- 1) Standard Wheel Chair
- 2) Folding Light Weight Wheel Chair
- 3) Rigid frame wheel chair
- 4) Special positioning wheel chair

**Electric powered wheel chair** is a wheelchair that is controlled by small analog joystick with the help of electric motor and that analog joystick is mounted on the wheelchair, rather than manual power. With the help of electric powered wheel chair disabled person can move without any care taker. In the recent years power-assisted wheelchair is the replacement of standard rear wheels with wheels that have small battery-powered motors in the hubs. Electric powered wheelchairs are of different types:

- 1) Rear Drive Power Chair
- 2) Front Wheel Drive Power Chair
- 3) Mid- Wheel Drive Power Chair

### 2.3 Advantages of Manual Wheel Chair

- 1) Less weight and easily affordable
- 2) Low cost due to light weight
- 3) Low maintenance cost

### Disadvantages of Manual Wheel Chair

- 1) Required more space due to non foldable
- 2) Footrest is non adjustable
- 3) Non adjustable back and arm rest
- 4) The patient cannot move for the bed or any other place only with the other help

### 2.4 Market Study

Market study is necessity to understand the product market sector, to know the how many competitors in the market, to study their product capacitance and market strategy, to bench mark the product. Following are the competitors present in the Indian market:

- 1) M. TECHNOLOGIES Manufacturer, Haryana
- 2) ANAND MEDICAL EXPORTS Manufacturer, New Delhi
- 3) PARAMOUNT SURGIMED LTD Manufacturer New Delhi
- 4) VISSCO INDUSTRIES Manufacturer, Pune
- 5) MANISH STEEL INDUSTRIES Manufacturer, Madhya Pradesh

### 2.5 Existing Methodology

- 1) K.Sudheer, T.V Janardhana rao, Ch.Shridevi M.s Madhan Mohan (2012): voice and gesture based electronic powered wheelchair using ARM used combination of speech and gesture recognition .In this speech recognition module, hidden markov model are used. The MEMS sensor is used and it senses the angle of hand. For Voice recognition the voice IC is used.
- 2) M. Prathyusha, K.S Roy, Mahboob Ali sheikh (2013 April): Voice and touch screen based direction and speed control of wheelchair. The

speech recognition system uses programmable speech recognition circuit. The speed controller works by varying the average voltage sent to the motor.

- 3) Rakhi A. Kalautri , D.K Chitre (2013): Used automatic gesture recognition system based on acceleration sensor here used is 2-axis .By calculating amount of tilt and output of tilt will decide to more in which direction.
- 4) Jinhua Zeng , Yaoru sun , Fang wang (2012): A natural hand gesture system for intelligent human-computer interaction and medical assistance. The hand gesture vocabulary in the system consist of 5 keys static hand gesture and 3 dynamic components. The hand motion in the vocabulary is limited to metacarpophalangeal joint (MCP) abduction and adduction of index finger , ring finger and little finger and the thumb basal joint (TBJ) radial abduction and adduction of the thumb.
- 5) Nurul Muthmainnah Mohd Noor, Salmiah Ahmad (2012): EOG based wheelchair control: The cornea of the eye is electrically positive relate to the back of the eye, the retina. The eye behaves as if it were a single dipole oriented from the retina to the cornea. Such cornea-retinal potentials are well established and are in the range of 0.0.5-3.5mV. Eye Movements thus produce a moving (rotating) dipole source and accordingly, signals that are a measure of the movement may be obtained. The recording and interpretation of the electrical activity of eye is called electro oculography. Its main application is in Ophthalmological diagnosis and in recording eye movements. Electrodes such as gold surface electrode, Ag-Cl electrodes are used to record the eye potential changes.
- 6) Alex Dev, Horizon C Chacko and Roshan Varghese, (ICCCE 2012): EYEBALL SENSING method for wheelchair control: The basic principle of this direction sensing is the color of the eyes. There are two main colour pigments in the human eyes. i.e., black and white. The colors show different wavelengths in the spectrum. White being the farthest colour in emits the lowest wavelength. So the wavelength of white light is chosen as the standard parameter. White light can be measured by infrared
- 7) Sandesh Pai, Sagar Ayare, Romil Kapadia October-2012: Camera based wheelchair control: The eye movement is tracked using a camera mounted on to the headgear. The headgear construction greatly simplifies the optics by using a micro lens video camera for dark-pupil tracking. The headgear is equipped with proper illumination. This headgear is interfaced to the

laptop/desktop via USB interface through which real time video of the eye is sent. The laptop/desktop hosts image processing software which processes the video feed from the camera and determines the position of the pupil. The laptop/desktop then sends signals corresponding to the pupil position to the micro-controller circuitry which drives the motor through motor driving circuit.

### III. APPLICATIONS OF SMART WHEELCHAIR

- 1) Hospitals
- 2) Sports
- 3) Physically handicapped individuals

### IV. CONCLUSION

We are introducing smart wheel chair which is multifunctional and can be controlled by various devices according to the comfort of patient. With the help of this multifunctional smart wheelchair patients who are disabled physically and mentally can make use of this smart wheel chair without the requirement of caretaker. So this is a multifunctional smart wheel chair the improvement and self-reliability of many disabled people. Modifications made in the established equipment meant for the disabled ones will be of great use in upcoming time. All data provided are precise to the best of our ability. The system uses Mobile phone so that the accuracy is increased. The sensor describes the parameters like light, Temperature, smoke, gas etc. The IR sensor is used for obstacle avoidance. An eye movement wheelchair is any motorized platform for a physical disability person to reduce or eliminate the user's task of driving a motorized wheelchair. The knowledge gained from product design education is used to analyze the existing wheel chair product by means of detailed Market research, product study, problem identification and detailing finalized concept.

### IV. REFERENCES

- [1] Ninama, Roshani, and Rutu Nayak. "Review on Eye Movement Controlled Wheelchair." *International Journal of Engineering Development and Research*. Vol. 2. No. 2 (June 2014). IJEDR, 2014.
- [2] Khadilkar, Shraddha Uddhav, and Narendra Wagdarikar. "Android phone controlled voice, gesture and touch screen operated smart wheelchair." *Pervasive Computing (ICPC), 2015 International Conference on*. IEEE, 2015.
- [3] Simpson, Richard C. "Smart wheelchairs: A literature review." *Journal of rehabilitation research and development* 42.4 (2005): 423.
- [4] Razak, S. "Design and implementation electrical wheel chair for disable able to stairs climbing by using hydraulic jack." *IOSR J 7.3* (2013): 82-92.
- [5] Lu, Tao, et al. "An embedded control system for intelligent wheelchair." *Engineering in Medicine and Biology Society, 2005. IEEE-EMBS 2005. 27th Annual International Conference of the*. IEEE, 2006.
- [6] Kumar, Banoth Kranthi. "INTERNATIONAL JOURNAL OF ENGINEERING SCIENCES & RESEARCH TECHNOLOGY."
- [7] Jiang, Lijun, et al. "Motor imagery controlled wheelchair system." *Industrial Electronics and Applications (ICIEA), 2014 IEEE 9th Conference on*. IEEE, 2014.
- [8] Sivakumar, M. Senthil, et al. "Speech controlled automatic wheelchair". *Information Science, Computing and Telecommunications (PACT), 2013 Pan African International Conference on*. IEEE, 2013.
- [9] Aruna, Chittineni, et al. "Voice recognition and touch screen control based wheel chair for paraplegic persons." *Green Computing Communication and Electrical Engineering (ICGCC), 2014 International Conference on*. IEEE, 2014.
- [10] Postolache, Octavian, et al. "Unobstrusive heart rate and respiratory rate monitor embedded on a wheelchair." *Medical Measurements and Applications, 2009. MeMeA 2009. IEEE International Workshop on*. IEEE, 2009.
- [11] Daisuke Chugo, Kenji Shiotani, Yuki Sakaida, Sho Yokota, Hiroshi Hashimoto "An Automatic Depressurization Assistance based on an Unconscious Body Motion of a Seated Patient on a Wheelchair" RIKEN-TRI Collaboration Center for Human-Interactive Robot Research (RTC) RIKEN (The Institute of Physical and Chemical Research) Nagoya, Aichi, Japan.
- [12] Chowdhury, Zamshed Iqbal, et al. "Design and implementation of Pyroelectric Infrared sensor based security system using microcontroller." *Students' Technology Symposium (TechSym), 2011 IEEE*. IEEE, 2011.
- [13] Fezari, Mohamed, Mounir Bousbia-salah, and Mouldi Bedda. "Voice and Sensor for More Security on an Electric Wheelchair." *Information and Communication Technologies, 2006. ICTTA'06. 2nd*. Vol. 1. IEEE, 2006.
- [14] Takahashi, Kazuki, Hirokazu Seki, and Susumu Tadakuma. "Safety driving control for electric

- power assisted wheelchair based on regenerative brake.*"Industrial Technology, 2006. ICIT 2006. IEEE International Conference on. IEEE, 2006.
- [15] Megalingam, Rajesh Kannan, et al. "**Power Aware Automatic Microcontroller Based Smart, College Electric Bell System with Time Display.**" MEMS, NANO, and Smart Systems (ICMENS), 2009 Fifth International Conference on. IEEE, 2009.
- [16] Fezari, Mohamed, and Abd-Erahman Khati. "**New speech processor and ultrasonic sensors based embedded system to improve the control of a motorised wheelchair.**" Design and Test Workshop, 2008. IDT 2008. 3rd International. IEEE, 2008.
- [17] Oskoei, Mohammadreza Asghari, and Huosheng Hu. "**Myoelectric based virtual joystick applied to electric powered wheelchair.**" Intelligent Robots and Systems, 2008. IROS 2008. IEEE/RSJ International Conference on. IEEE, 2008.
- [18] Fezari, Mohamed, Abderrahmene Khati, and Hamza Attoui. "**Embedded system based on multiprocessors to improve the control of a motorised wheelchair.**" Design & Technology of Integrated Systems in Nanoscal Era, 2009. DTIS'09. 4th International Conference on. IEEE, 2009.
- [19] Fezari, Mohamed, and Mounir Bousbia-Salah. "**Speech and sensor in guiding an electric wheelchair.**" Automatic Control and Computer Sciences 41.1 (2007): 39-43.
- [20] Seki, Hirokazu, and Yoshiaki Takahashi. "**Downward slope driving control for electric powered wheelchair based on capacitor regenerative brake.**" Industrial Electronics, 2009. IECON'09. 35th Annual Conference of IEEE. IEEE, 2009.
- [21] Tanohata, Naoki, Hiroki Murakami, and Hirokazu Seki. "**Battery friendly driving control of electric power-assisted wheelchair based on fuzzy algorithm.**" SICE Annual Conference 2010, Proceedings of. IEEE, 2010.
- [22] Dilok Puanhvuany, y odchanan W ongsawat "**Semi-Automatic P300-Based Brain-Controlled Wheelchair** " Proceedings of 2012 ICME International Conference on Complex Medical Engineering July I - 4, Kobe, Japan.
- [23] Augie Widyotriatmo, Saqi Khudi Rauzanfiqr, Suprijanto "**A Modified PID Algorithm for Dynamic Control of an Automatic Wheelchair**" 2012 IEEE Conference on Control, Systems and Industrial Informatics (ICCSII) Bandung, Indonesia, September 23-26,2012.
- [24] Chun-Rong Huang, Member, IEEE, Pau-Choo (Julia) Chung, Fellow, IEEE, Kuo-Wei Lin, and Sheng-Chieh Tseng "**Wheelchair Detection Using Cascaded Decision Tree**" IEEE TRANSACTIONS ON INFORMATION TECHNOLOGY IN BIOMEDICINE, VOL. 14, NO. 2, MARCH 2010.
- [25] Octavian Postolache, Joaquim Mendes "**Unobstrusive Heart Rate and Respiratory Rate Monitor Embedded on a Wheelchair**" MeMeA 2009 - International Workshop on Medical Measurements and Applications Cetraro, Italy May 29-30, 2009.
- [26] Anthony Remazeilles, Christophe Leroux, Gerard Chalubert, Laurent Delahoche, Bruno Marhic, Isabelle Laffont and Nicolas Biard "**Automatic Grasping Task with a Catadioptric Sensor for Disabled People**" 2008 10th Intl. Conf. on Control, Automation, Robotics and Vision Hanoi, Vietnam, 17-20 December 2008.
- [27] Mohamed Fezari, Abd-Erahman Khati "**New speech processor and Ultrasonic Sensors Based Embedded system to Improve the Control of a Motorised Wheelchair**" Laboratory of Automatic and Signals Annaba University of Annaba, Faculty of Engineering,Algeria.
- [28] Chandan Banerjee, Harish Gupta, Kumar Sushobhan "**Low Cost Speech and Vision Based Wheel Chair For Physically Challenged**" Electronics & Communication Engineering, Vellore Institute of Technology University, Vellore, India.
- [29] Kailas, A., "**Basic human motion tracking using a pair of gyro + accelerometer MEMS devices,**" in *e-Health Networking, Applications and Services (Healthcom), 2012 IEEE 14th International Conference on* , vol., no., pp.298-302, 10-13 Oct. 2012.
- [30] Rahulanker, R.; Ramanarayanan, V., "**Battery assisted wheel chair,**" in *Power Electronics, 2006. IICPE 2006. India International Conference on* , vol., no., pp.167-171, 19-21 Dec. 2006  
doi: 10.1109/IICPE.2006.468536
- [31] Croteau, C. (1998), "**Wheel chair mobility hand book**", Park press publishing.